

# 2009-12-21 Linux kernel driver that handles IRQ

## Plan

- make minimalistic driver that requests IRQ on load and release it on unload;
- pass IRQ no. as a module parameter;
- (variation) make ISR lock spinlock and not release it; see how it looks;
- (extra) modify qemu to allow emitting IRQ from monitor;

## Worklog

- get your future roots: build this directory tree, put busybox for i386 into bin, make symlinks to it, copy device nodes from system /dev

```
bin/
├── busybox*
├── cat -> busybox*
├── df -> busybox*
├── du -> busybox*
├── insmod -> busybox*
├── less -> busybox*
├── ln -> busybox*
├── ls -> busybox*
├── lsmod -> busybox*
├── mount -> busybox*
├── rmmod -> busybox*
├── sh -> busybox*
├── top -> busybox*
├── vi -> busybox*
└── dev/
    ├── pts/
    ├── console
    ├── kmsg
    ├── loop0
    ├── loop1
    ├── loop2
    ├── loop3
    ├── loop4
    ├── loop5
    ├── loop6
    ├── loop7
    ├── mem
    ├── null
    ├── ptmx
    └── random
```

```

├── systty
├── tty
├── tty0
├── tty1
├── tty2
├── urandom
├── zero
├── lib/
│   └── modules/
│       └── 2.6.33-rc1/
├── proc/
├── sbin/
├── sys/
├── tmp/
├── init*
└── test.ko

```

- make /init like this:

```

#!/bin/sh

mount -t proc proc /proc
mount -t sysfs sysfs /sys
mount -t devpts devpts /dev/pts

while :
do
  /bin/sh
done

```

- get a linux, configure and compile it:

```

git clone
git://git.kernel.org/pub/scm/linux/kernel/git/torvalds/linux-2.6.git
make ARCH=i386 defconfig
# turn off networking as we don't need it
# turn on initramfs:
# General setup --->
# [*] Initial RAM filesystem and RAM disk (initramfs/initrd) support
# (/home/dumb/ws/ii/games-build/games/src/lkm/rootfs) Initramfs source
file(s)
make ARCH=i386 menuconfig
make ARCH=i386 -j3 bzImage

```

- make test.c, module source:

```

#include <linux/kernel.h>
#include <linux/init.h>
#include <linux/module.h>
#include <linux/irq.h>
#include <linux/interrupt.h>

```

```
static irqreturn_t test_irq_handler(int i, void *dev)
{
    static spinlock_t lock = __SPIN_LOCK_UNLOCKED(lock);
    unsigned long flags;

    printk(KERN_INFO "%s(%d, %p)\n", __func__, i, dev);
    spin_lock_irqsave(&lock, flags);
    printk(KERN_INFO "flags: %lx\n", flags);
    spin_unlock_irqrestore(&lock, flags);
    return IRQ_HANDLED;
}

static int test_irq;
static int test_irq_no;
#define IRQ_NO test_irq_no

module_param(test_irq_no, int, 13);
MODULE_PARM_DESC(test_irq_no, "requested IRQ line");

static int __init test_init(void)
{
    int rc;
    printk(KERN_INFO "%s\n", __func__);
    rc = request_irq(IRQ_NO, test_irq_handler, IRQF_SHARED,
"test_device", &test_irq);
    printk(KERN_INFO "request_irq(%d, %p): %d\n", IRQ_NO, &test_irq,
rc);
    if (!rc)
        test_irq = IRQ_NO;
    return 0;
}

static void __exit test_exit(void)
{
    printk(KERN_INFO "%s\n", __func__);
    if (test_irq)
        free_irq(test_irq, &test_irq);
}

module_init(test_init);
module_exit(test_exit);

MODULE_AUTHOR("jcmvbkbc");
MODULE_LICENSE("GPL");
```

- make a Makefile for it:

```
PWD = $(shell pwd)
EXTRA_CFLAGS += -Wall

obj-m += test.o
```

```
default: modules
```

```
modules clean:  
    make -C $(KDIR) M=$(PWD) $@
```

- compile it like this: `make -C "$PWD/linux-2.6" ARCH=i386 M="$PWD" modules`
- copy `test.ko` to the `rootfs /` and rebuild `bzImage`
- run it in `qemu`: `qemu -kernel bzImage`
- load module inside the shell in `qemu`: `insmod test.ko test_irq_no=1`
- press and release keys (`irq 1` is keyboard interrupt)
- see it there: `cat /proc/interrupts`
- unload it: `rmmod test`

Code: <ftp://kkv.spb.su/pub/home/dumb/ws/ltd/20091221/>

## Conclusion

- `initramfs` is fun: `bzImage` holds `rootfs` and re-builds it even if kernel code is not changed;
- `spinlock` re-acquisition locks up hard;
- `qemu` internal hardware objects are not that easily navigable - to be continued;

[linux](#), [lkm](#), [qemu](#), [ltd](#)

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